

Semantics-based generation of verification conditions by program specialization

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Talk Outline

- Partial Correctness properties and Verification Conditions (VCs)
- Constraint Logic Programming as a metalanguage for representing
 - the imperative program
 - the semantics of the imperative language
 - the property to be verified
- CLP program specialization for generating VCs
 - using unfold / fold transformation rules
- Experimental evaluation

Partial Correctness and VCs

Given the partial correctness property (Hoare triple):

$$\{n \geq 1\} \quad x=0; y=0; \quad \{y > x\}$$
$$\mathbf{while} (x < n) \{x=x+1; y=y+2\}$$

Verification Conditions: formulas whose satisfiability implies correctness

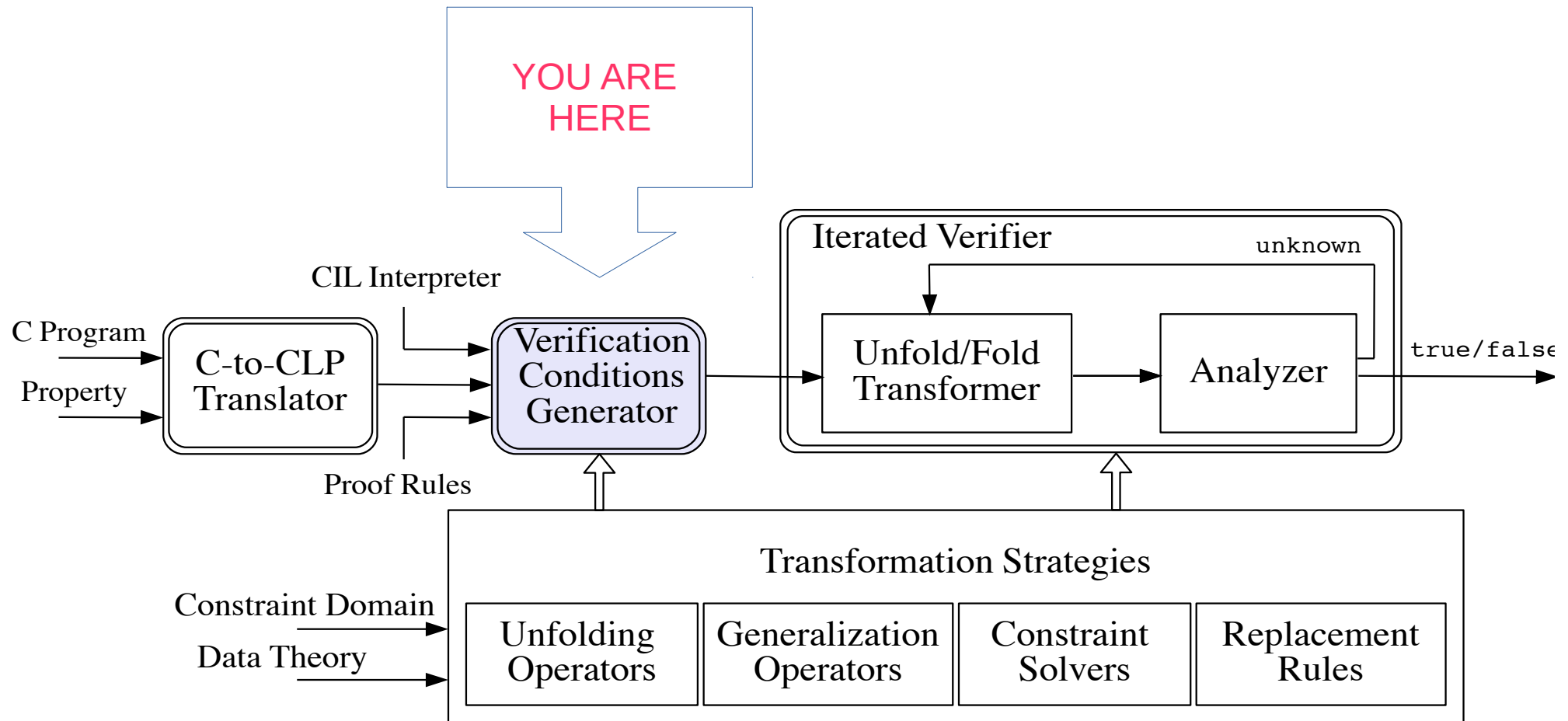
Verification conditions (VCs) as Horn clauses with constraints (CLP)

$n \geq 1 \wedge x=0 \wedge y=0 \rightarrow P(x,y,n)$	(Initialization)
$P(x,y,n) \wedge x < n \rightarrow P(x+1,y+2,n)$	(Loop body execution)
$P(x,y,n) \wedge x \geq n \wedge y \leq x \rightarrow \text{false}$	(Loop exit)

VCs satisfiability can (possibly) be checked by using Horn solvers and Satisfiability Modulo Theory (SMT) solvers like

- Duality (McMillan), Eldarica (Ruemmer et al.), MathSAT (Cimatti et al.), SeaHorn (Gurfinkel et al.), Z3 (Bjorner & De Moura), CHA (Gallagher et al.), QARMC / HSF (Rybalchenko et al.), TRACER (Jaffar et al.), VeriMAP (De Angelis et al.)

VeriMAP architecture



VCS GENERation

Standard approach

- VCGEN algorithm is tailored to the syntax and the semantics of the imperative programming language
- **Cons:** changing the programming language or its semantics requires **rewriting** the VCGEN algorithm

Semantics-based approach

[Cousot SAS'97, Peralta et al. SAS'98, J Strother Moore CHARME'03]

- VCGEN algorithm is **parametric** wrt programming language semantics
- **Pro:** the same VCGEN algorithm can be used for different programming languages and semantics

Our semantics-based approach

- uses CLP program specialization
- Correctness of VC generation follows from correctness of unfold/fold transformation rules
- Flexibility and efficiency

Encoding Imperative Programs

- Imperative language: subset of CIL (C Intermediate Language)
 - assignments, conditionals, jumps, recursive function calls, abort
 - loops translated to conditionals and jumps
- Commands encoded as facts: **at(Label, Cmd)**

Program *gcd*

```
int x, y;

int sub(int a, int b) {
    int r = a-b;           l1
    return r;              l2
}

void main() {
    while (x!=y)           l3
        if (x>y)           l4
            x = sub(x,y);  l5
        else
            y = sub(y,x);  l7
}
```

CLP encoding of *gcd*

```
fun(sub,[a,b],[r],1).
at(1,asgn(r,minus(a,b))). % l1
at(2,return(r)).          % l2

fun(main,[],[],3).
at(3,ite(neq(x,y),4,h)).
at(4,ite(gt(x,y),5,7)).
at(5,asgn(x,call(sub,[x,y]))).
at(6,goto(3)).
at(7,asgn(y,call(sub,[y,x]))).
at(8,goto(3)).
at(h,halt).
```

Encoding the Operational Semantics

Configurations: $\mathbf{cf(LC, Env)}$ program execution state

- **LC** labeled command: a term of the form $\mathbf{cmd(L,C)}$
 - **L** label, **C** command
- **Env** environment: a pair $\mathbf{(D,S)}$
 - **D** global environment, **S** local environment
 - Environments as lists of pairs $\mathbf{[(x,X),(y,Y),(z,Z)]}$

Operational semantics: transition relation \mathbf{tr} between configurations

$$\mathbf{tr(cf(LC1,E1), cf(LC2,E2))}$$

Multiple steps reachability (reflexive, transitive closure of \mathbf{tr})

$\mathbf{reach(C,C)}$.

$\mathbf{reach(C,C2) :- tr(C,C1), reach(C1,C2)}$.

Encoding the Operational Semantics

assignment $x=e;$

<code>tr(cf(cmd(L, asgn(X,expr(E))), (D,S)),</code>	<code>source configuration</code>
<code>cf(cmd(L1,C), (D1,S1))) :-</code>	<code>target configuration</code>
<code>eval(E,(D,S),V),</code>	<code>evaluate expression</code>
<code>update((D,S),X,V,(D1,S1)),</code>	<code>update environment</code>
<code>nextlab(L,L1),</code>	<code>next label</code>
<code>at(L1,C).</code>	<code>next command</code>

Encoding the Operational Semantics

function call

$x=f(e_1,\dots,e_n);$

“return” case

$tr(cf(cmd(L,asgn(X,call(F,Es))), (D,S)),$	$(D,S),$	source configuration
$cf(cmd(L2,C2),$	$(D2,S2))) :-$	target configuration
$eval_list(Es,D,S,Vs),$		evaluate function parameters
$build_funenv(F,Vs,FEnv),$		build function environment
$firstlab(F,FL), at(FL,C),$		first label and command function def
$reach(cf(cmd(FL,C), (D,FEnv)),$		function execution
$cf(cmd(LR,return(E)),(D1,S1))),$		return
$eval(E,(D1,S1),V),$		evaluate returned expression
$update((D1,S),X,V,(D2,S2)),$		update caller environment
$nextlab(L,L2), at(L2,C2).$		next label and command

Multi-Step Operational Semantics

Encoding Partial (In)Correctness

Partial correctness property P

$$\{x \geq 1 \wedge y \geq 1\} \text{ gcd } \{x \geq 0\}$$

CLP encoding of (in)correctness.

CLP program I

```
incorrect :- initConf(Cf), reach(Cf,Cf1), errorConf(Cf1).
```

...

```
initConf(cf(C, [(x,X),(y,Y)])) :- at(3,C), X>=1, Y>=1.
```

```
errorConf(cf(C, [(x,X),(y,Y)])) :- at(h,C), X=< -1.
```

Thm. Correctness of CLP Encoding

property P does not hold iff incorrect \in M(I)

where: M(I) least LIA model of the CLP program I

Undecidable problem. Even if decidable, very hard to check.

Unfold/Fold program specialization for “removing the interpreter”.

Unfold/Fold program specialization

incorrect :- initConf(C), reach(C, C1), errorConf(C1).

- **UNFOLDING** (replace initConf(C) with the body of its definition)

incorrect :- X>=1, Y>=1, reach(cf(cmd(3, ite(neq(x, y)), 4, h), [(x, X), (y, Y)], []), C1), errorConf(C1).

- **UNFOLDING** (wrt errorConf(C1))

incorrect :- X>=1, Y>=1, X1=<-1, reach(cf(cmd(3, ite(neq(x, y)), 4, h), [(x, X), (y, Y)], []), cf(cmd(h, halt), [(x, X1), (y, Y1)], []))).

- **DEFINITION-INTRODUCTION** (with constraint generalization)

new3(X, Y, X1, Y1) :- reach(cf(cmd(3, ite(neq(x, y)), 4, h), [(x, X), (y, Y)], []), cf(cmd(h, halt), [(x, X1), (y, Y1)], []))).

- **FOLDING** (replace an instance of the body of a definition by its head)

incorrect :- X>=1, Y>=1, X1=<-1, new3(X, Y, X1, Y1).

VCG strategy

Input: program I (incorrect, at, tr, reach, ...)

Output: VCs (new predicates)

VCs := \emptyset ;

Defs := {incorrect :- initConf(C), reach(C, C1), errorConf(C1)};

while there exists d in Defs to be processed **do**

 Cls = **UNFOLDING**(d, I);

 Defs = Defs \cup **DEFINITION-INTRODUCTION**(Cls);

 VCs = VCs \cup **FOLDING**(Cls, Defs);

 mark d as processed;

done

Thm. Termination and correctness of the VCG strategy

(i) the VCG strategy terminates

(ii) incorrect $\in M(I)$ iff incorrect $\in M(\text{VCs})$

VCS Multi-Step Semantics

```
incorrect :- X>=1,Y>=1,X1=<-1, new3(X,Y, X1,Y1).
new3(X,Y, X1,Y1):- X+1=<Y, new4(X,Y, X1,Y1).      % loop execution
new3(X,Y, X1,Y1):- X>=Y+1, new4(X,Y, X1,Y1).      % loop execution
new3(X,Y, X,Y):- X=Y.                             % loop exit
new4(X,Y, X3,Y3):- X>=Y+1, A=X, B=Y, X2=R1,        % then branch
                    new6(X,Y,A,B,R, X1,Y1,A1,B1,R1),
                    new3(X2,Y1, X3,Y3).
new4(X,Y, X3,Y3):- X=<Y,   A=Y, B=X, Y2=R1,        % else branch
                    new6(X,Y,A,B,R, X1,Y1,A1,B1,R1),
                    new3(X1,Y2, X3,Y3).
new6(X,Y,A,B,R, X,Y,A,B,R1) :- R1=A-B.           % sub function call
```

VCS generated by using the multi-step semantics

- Non linear recursive: multiple atoms in the body (e.g. new6, new3)
- Predicate arity is even (variables for source and target configurations)

Small-Step Semantics

We need to keep a stack of activation frames

Function call: push an element on top of the stack

```
tr(cf(cmd(L,asgn(X,call(F,Es))),D,T),
   cf(cmd(FL,C),          D,[frame(L1,X,FEnv)|T])) :-
    nextlab(L,L1),
    loc_env(T,S), eval_list(Es,D,S,Vs),
    build_funenv(F,Vs,FEnv),
    firstlab(F,FL), at(FL,C).
```

L1 label where to jump after returning

X stores the value returned by the function call

FEnv local environment used during the execution of the function call

Function return: pop an element from the stack

```
tr(cf(cmd(L,return(E)),D,[frame(L1,X,S) |T]),
   cf(cmd(L1,C),          D1,T1)) :-
    eval(E,D,S,V),
    update((D,T),X,V,(D1,T1)),
    at(L1,C).
```

Small-Step Semantics

Encoding correctness when using the Small-Step semantics

```
incorrect :- initConf(C), reach(C).  
reach(C) :- tr(C,C1), reach(C1).  
reach(C) :- errorConf(C).
```

VCs generated by using the Small-Step semantics

```
incorrect :- X>=1, Y>=1, new3(X,Y).  
new3(X,Y) :- X=<-1, Y=X.  
new3(X,Y) :- X+1=<Y, new4(X,Y).  
new3(X,Y) :- X>=1+Y, new4(X,Y).  
new4(X,Y) :- X>=Y+1, new6(X,Y).  
new4(X,Y) :- X=<Y, new7(X,Y).  
new6(X,Y) :- A=X, B=Y, new11(X,Y,A,B,R).  
new7(X,Y) :- A=Y, B=X, new8(X,Y,A,B,R).  
new8(X,Y,A,B,R) :- R1=A-B, new9(X,Y,A,B,R1).  
new9(X,Y,A,B,R) :- Y1=R, new3(X,Y1).  
new11(X,Y,A,B,R) :- R1=A-B, new12(X,Y,A,B,R1).  
new12(X,Y,A,B,R) :- X1=R, new3(X1,Y).
```

- Linear recursive (at most one atom in the body)
- More predicates and clauses than in Multi-Step semantics VCs
Multiple predicates for the calls to the sub function (e.g. new11 and new8)
- Half the variables w.r.t. MS semantics VCs

Semantics variations

- Side-effect free functions
 - `new6(X,Y,A,B,R, X1,Y1, A,B,R1) :- R1=A-B. % sub`
- Undefined functions and assertions
- Stack traces in case of aborted execution
- Output commands
- Mapping the VCs to source code
- Tuning the unfolding strategy

```
incorrect :- X>=1,Y>=1,X1=<-1, new3(X,Y ,X1,Y1).
new3(X,Y, X2,Y2) :- X1=X-Y, X>=Y+1, new3(X1,Y, X2,Y2).
new3(X,Y, X2,Y2) :- Y1=Y-X, X+1=<Y, new3(X,Y1, X2,Y2).
new3(X,Y, X,Y) :- X=Y.
```


Experimental evaluation

- 320 verification problems written in the C language
 - from TACAS SV-COMP, other public benchmarks
- Performance improvements wrt previous VCG strategy
 - More efficient constraint satisfiability checker (rows 2,4)
 - Replace sequences of unfolding steps with Prolog calls (3,4)

		n	t_{VCG}	t'_{VCG}
Small-step	1. SS_o^p	216	159.45	159.45
	2. SS_o^s	320	1235.96	35.58
	3. SS_f^p	317	4254.71	34.71
	4. SS_f^s	320	218.57	11.25
Multi-step	5. MS	318	364.43	7.70

Table 3. Times (in seconds) taken for the VC generation using different language semantics and settings. The time limit is five minutes. n is the number of programs out of 320, for which the VCs were generated.

Experimental evaluation

- Checking the satisfiability of the VCs
 - QARMC, Z3 (PDR), MathSAT (IC3), HSF+QARMC

		Small-step(SS_f^s)			Multi-step (MS)			HSF + QARMC
		QARMC	Z3	MSATIC3	QARMC	Z3	MSATIC3	
c	Correct answers	221	209	212	212	196	178	189
s	safe problems	164	150	160	161	143	149	158
u	unsafe problems	57	59	52	51	53	29	31
i	Incorrect answers	5	0	2	3	0	0	12
f	false alarms	3	0	0	1	0	0	3
m	missed bugs	2	0	2	2	0	0	9
to	Timed-out problems	94	111	106	103	122	140	119
n	Total problems	320	320	320	318	318	318	320
t_{VCG}	VCG time	218.57	218.57	218.57	364.43	364.43	364.43	N/A
st	Solving time	3423.75	3446.84	3008.81	2924.62	2618.21	1616.81	N/A
tt	Total time	3642.32	3665.41	3227.38	3289.05	2982.64	1981.24	631.11
at	Average Time	16.12	17.54	15.08	15.30	15.30	11.13	3.14

Table 4. Verification results using QARMC, Z3, MSATIC3, and HSF+QARMC. The time limit is five minutes. Times are in seconds.

Demo

Hope it works... :-)

Conclusions

- Semantics-based VC generation
 - Semantics of the programming language as a parameter
 - Flexible and quite efficient
 - Viable from a practical point of view
- Future work
 - More languages
 - More properties
- Benchmarks, VCs and tool at <http://map.uniroma2.it/vcgen/>

The end

Thank you!

```

1. tr(cf(cmd(L,asgn(X,expr(E))), (D,S)), cf(cmd(L1,C), (D1,S1))) :-
    eval(E, (D,S),V), update((D,S),X,V,(D1,S1)), nextlab(L,L1), at(L1,C).
2a. tr(cf(cmd(L,asgn(X,call(F,Es))), (D,S)), cf(cmd(LA,abort), (bot,D1,S))) :-
    eval_list(Es,D,S,Vs), build_funenv(F,Vs,FEnv), firstlab(F,FL), at(FL,C),
    reach(cf(cmd(FL,C), (D,FEnv)), cf(cmd(LA,abort), (bot,D1,S1))).
2r. tr(cf(cmd(L,asgn(X,call(F,Es))), (D,S)), cf(cmd(L2,C2), (D2,S2))) :-
    eval_list(Es,D,S,Vs), build_funenv(F,Vs,FEnv), firstlab(F,FL), at(FL,C),
    reach(cf(cmd(FL,C), (D,FEnv)), cf(cmd(LR,return(E)), (D1,S1))),
    eval(E, (D1,S1),V), update((D1,S),X,V,(D2,S2)), nextlab(L,L2), at(L2,C2).
3. tr(cf(cmd(L,abort), (D,S)), cf(cmd(L,abort), (bot,D,S))).
4t. tr(cf(cmd(L,ite(E,L1,L2)), (D,S)), cf(cmd(L1,C), (D,S))) :- beval(E,(D,S)), at(L1,C).
4f. tr(cf(cmd(L,ite(E,L1,L2)), (D,S)), cf(cmd(L2,C), (D,S))) :- beval(not(E),(D,S)), at(L2,C).
5. tr(cf(cmd(L,goto(L1)), (D,S)), cf(cmd(L1,C), (D,S))) :- at(L1,C).
6. update((D,S),X,V,(D1,S)) :- global(X), update_glocal(D,X,V,D1).
7. update((D,S),X,V,(D,S1)) :- local(X), update_glocal(S,X,V,S1).
8. reach(C,C).
9. reach(C,C2) :- tr(C,C1), reach(C1,C2).

```

Table 2. The CLP interpreter for the multi-step operational semantics *MS*: the clauses for `tr` and `reach`.