

Verification of Imperative Programs through Transformation of Constraint Logic Programs

Emanuele De Angelis¹, Fabio Fioravanti¹,
Alberto Pettorossi², and Maurizio Proietti³

¹University of Chieti-Pescara 'G. d'Annunzio', Italy

²University of Rome 'Tor Vergata', Italy

³CNR - Istituto di Analisi dei Sistemi ed Informatica, Rome, Italy

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Proving Partial Correctness of Imperative Programs

Given the *program prog*:

```
x=0; y=0;  
while (x < n) {x=x+1; y=y+2}
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and the *specification*:

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{n ≥ 1} prog {y > x}
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Generate the *verification conditions* (VCs):

1. $x=0 \wedge y=0 \wedge n \geq 1 \rightarrow P(x, y, n)$
2. $P(x, y, n) \wedge x < n \rightarrow P(x+1, y+2, n)$
3. $P(x, y, n) \wedge x \geq n \rightarrow y > x$

Initialization

Loop invariant

Exit

and prove they are *satisfiable*, i.e., we can find an interpretation for P that makes the VCs true.

Proving Satisfiability of Verification Conditions

The *interpretation*

$$P(x, y, n) \equiv (x=0 \wedge y=0 \wedge n \geq 1) \vee y > x$$

makes the *VCS true*

$$1'. \quad x=0 \wedge y=0 \wedge n \geq 1 \rightarrow (x=0 \wedge y=0 \wedge n \geq 1) \vee y > x$$

$$2'. \quad ((x=0 \wedge y=0 \wedge n \geq 1) \vee y > x) \wedge x < n \\ \rightarrow (x+1=0 \wedge y+2=0 \wedge n \geq 1) \vee y+2 > x+1$$

$$3'. \quad ((x=0 \wedge y=0 \wedge n \geq 1) \vee y > x) \wedge x \geq n \rightarrow y > x$$

and hence the specification $\{n \geq 1\} \text{ prog } \{y > x\}$ is *valid*.

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Problem: How to find the interpretation for P automatically?

Methods Based on Horn Clauses with Constraints (CLP)

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- Methods for proving the satisfiability of VCs in the framework of CHC/CLP:
 - CounterExample Guided Abstraction Refinement, Interpolation, Satisfiability Modulo Theories [McMillan, Rybalchenko, Björner, Poppea et al.]
 - Symbolic execution of CLP [Jaffar, Navas, Santosa et al.]
 - Static Analysis and *Transformation of CLP* [Gallagher, Albert, DFPP et al.]

A Transformation-based Method

- Apply to V transformations that *preserve the least model*:
 1. $x=0 \wedge y=0 \wedge n \geq 1 \rightarrow P(x, y, n)$ *Constrained fact*
 2. $P(x, y, n) \wedge x < n \rightarrow P(x + 1, y + 2, n)$
 4. $P(x, y, n) \wedge x \geq n \wedge y \leq x \rightarrow \text{false}$

and derive the *equisatisfiable* V' :

5. $Q(x, y, n) \wedge x < n \wedge x > y \wedge y \geq 0 \rightarrow Q(x + 1, y + 2, n)$
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No constrained facts: V' satisfiable with $Q(x, y, n) \equiv \text{false}$.

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- **Problem**: How to transform V into V' automatically?

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- **Problem**: How to transform V into V' automatically?
- Some transformation strategies for programs over integers [PEPM-13] and arrays [VMCAI-14].

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- Constraint Logic Programming as a *metalanguage* for representing
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 - the semantics of the imperative language (*interpreter*)
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- *Recursively* defined properties
- Experimental evaluation: The VeriMAP system

CLP with integer constraints

- A CLP *clause* is an implication $c \wedge G \rightarrow H$, written as:

$$H \text{ :- } c, G.$$

where H is an atom, c is a constraint, and G is a conjunction of atoms

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- A CLP *program* is a set of CLP clauses
- Semantics: *least model* of the program with the fixed interpretation of constraints.

Imperative Programs over Integers

- We consider an imperative language with integer variables, assignment, if-else, while-loop, and goto.
- Program *increase*:

```
while(x < n){  
    x=x+1;  
    y=x+y;  
}
```

- Partial Correctness Specification

$$\{x = 0 \wedge y = 0\} \text{ increase } \{x \leq y\}$$

Encoding of an Imperative Program into CLP

A program is represented as a set of atoms `at(label, command)`.

Program *increase*:

```
l0 :   while(x < n){  
l1 :     x=x+1;  
l2 :     y=x+y;  
l3 :   }
```

CLP encoding of *increase*:

```
at(l0, ite(less(int(x), int(n)), l1, lh)).  
at(l1, asgn(int(x), plus(int(x), int(1)))).  
at(l2, asgn(int(y), plus(int(x), int(y)))).  
at(l3, goto(l0)).  
at(lh, halt).
```


A *transition semantics* is defined by:

- a set of *configurations*, i.e., a CLP term: $\text{cf}(C, S)$

where:

- C is a labeled *command*
- S is a *store*,
i.e., a list of [variable identifier, value] pairs:

$[[\text{int}(x), 2], [\text{int}(y), 3]]$

- a *transition relation*: $\text{tr}(\text{cf}(C, S), \text{cf}(C1, S1))$

<pre>L: Id=Expr</pre>	<pre>tr(cf(cmd(L,asgn(Id,Expr)),S), cf(cmd(L1,C1),S1)) :- aeval(Expr,S,V), <i>evaluate expression</i> update(Id,V,S,S1), <i>update store</i> nextlabel(L,L1), <i>next label</i> at(L1,C1). <i>next command</i></pre>
<pre>L: if (Expr) { goto L1: } else goto L2 }</pre>	<pre>tr(cf(cmd(L,ite(Expr,L1,L2)),S), cf(C,S)) :- beval(Expr,S), <i>expression is true</i> at(L1,C). <i>next command</i> tr(cf(cmd(L,ite(Expr,L1,L2)),S), cf(C,S)) :- beval(not(Expr),S), <i>expression is false</i> at(L2,C). <i>next command</i></pre>
<pre>L: goto L1</pre>	<pre>tr(cf(cmd(L,goto(L1)),S), cf(C,S)) :- at(L1,C). at(L1,C). <i>next command</i></pre>

CLP encoding of (in)correctness

Given the specification $\{\varphi_{init}\} prog \{\psi\}$ define $\varphi_{error} \equiv \neg\psi$

Definition (Program Incorrectness)

A program $prog$ is *incorrect* w.r.t. φ_{init} and φ_{error} if from an initial configuration satisfying φ_{init} it is possible to reach a final configuration satisfying φ_{error} .

Otherwise, program $prog$ is *correct*.

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Definition (CLP encoding of incorrectness: The interpreter *Int*)

incorrect :- initConf(X), reach(X).

reach(X) :- tr(X,Y), reach(Y). | *reachability*

reach(X) :- errorConf(X). |

initConf(X) \equiv X is a configuration satisfying φ_{init}

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Theorem (Correctness of Encoding)

prog is correct iff **incorrect** $\notin M(Int)$ (the least model of *Int*)

Partial Correctness Specification

 $\{x = 0 \wedge y = 0\}$ φ_{init} *increase* $\{x \leq y\}$ ψ $\{x > y\}$ $\varphi_{error} \equiv \neg\psi$

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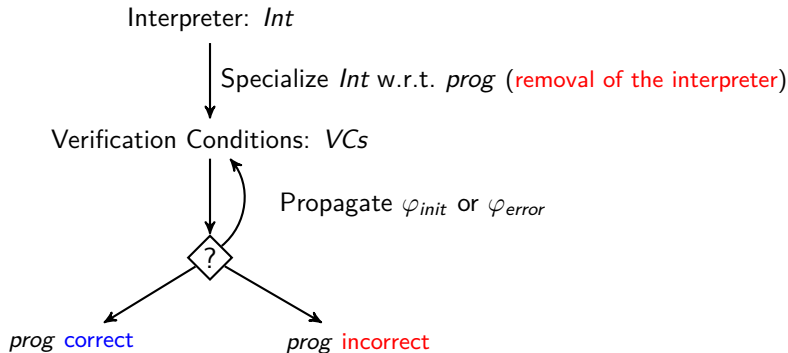
Initial and Error Configurations

```

initConf(cf(cmd(0,ite(...)), [[int(x),X],[int(y),Y],[int(n),N]]))
    :- X=0, Y=0.            $\varphi_{init}$ 
errorConf(cf(cmd(h,halt), [[int(x),X],[int(y),Y],[int(n),N]]))
    :- X>Y.               $\varphi_{error}$ 

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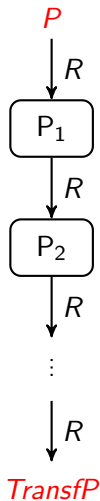
The Transformation-based Verification Method



- $prog$ correct if no constrained facts appear in the VCs .
- $prog$ incorrect if the fact incorrect. appears in the VCs .

Unfold/Fold Program Transformation

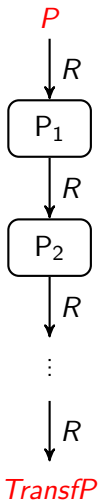
[Burstall-Darlington 77, Tamaki-Sato 84, Etalle-Gabbrielli 96]



- transformation *rules*:
 $R \in \{ \text{Definition, Unfolding, Folding, Clause Removal} \}$

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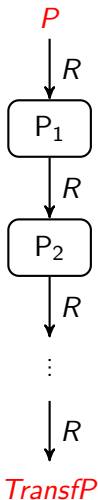
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- the transformation rules *preserve the least model*:

$\text{incorrect} \in M(P) \text{ iff } \text{incorrect} \in M(\text{Transf}P)$

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- the rules must be guided by a *strategy*.

Rules for Transforming CLP Programs

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R2. **Unfolding.** A symbolic evaluation step (resolution)

given $H :- c, \underline{A}, G$

$$\underline{A} :- d_1, G_1, \dots, \underline{A} :- d_m, G_m$$

derive $H :- c, d_1, G_1, G, \dots, H :- c, d_m, G_m, G$

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R3. **Folding.** Matching a predicate definition (e.g., a loop invariant)

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R4. **Clause Removal.** Removal of clauses with unsatisfiable constraint or subsumed by others

The Transformation Strategy

Transform(P)

```
TransfP =  $\emptyset$ ;  
Defs = { incorrect :- initConf(X), reach(X) };  
while  $\exists cl \in \text{Defs}$  do  
  Cls = Unfold(cl);  
  Cls = ClauseRemoval(Cls);  
  Defs = (Defs - {cl})  $\cup$  Define(Cls);  
  TransfP = TransfP  $\cup$  Fold(Cls, Defs);  
od
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Theorem (Termination and Correctness of the Transformation Strategy)

- *Transform(P)* terminates for all *P*;
- **incorrect** $\in M(P)$ iff **incorrect** $\in M(\text{TransfP})$

Generalization Strategies

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• Given $p(X) :- c(X,Y), \underline{q(Y)}.$

Introduce $\text{newp}(Y) :- d(Y), \underline{q(Y)}.$

where $c(X,Y) \rightarrow d(Y)$ ($d(Y)$ is a *generalization* of $c(X,Y)$)

and *fold*: $p(X) :- c(X,Y), \text{newp}(Y).$

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- Generalization strategies based on *widening* and *convex-hull* of linear constraints.

Generating Verification Conditions via Specialization

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The Specialized Interpreter for *increase* (Verification Conditions)

```
incorrect :- X=0, Y=0, new1(X,Y,N).  
new1(X,Y,N) :- X < N, X1=X+1, Y1=X1+Y, new1(X1,Y1,N).  
new1(X,Y,N) :- X ≥ N, X > Y.
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- New predicates correspond to a subset of the *program points*:
`new1(X,Y,N) :- reach(cf(cmd(0,ite(...)),
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 $\text{new1}(X,Y,N) :- \text{reach}(\text{cf}(\text{cmd}(0, \text{ite}(\dots)),$
 $[[\text{int}(x), X], [\text{int}(y), Y], [\text{int}(n), N]]))$.
- The fact *incorrect.* is not in VCs: we cannot infer that *increase* is **incorrect**.
A constrained fact is in VCs: we cannot infer that *increase* is **correct**.

The verification conditions VCs are specialized w.r.t. the initial configuration.

Specialized Verification Conditions for *increase*

... propagating the constraint $X=0, Y=0$.

```
incorrect :- N > 0, X1 = 1, Y1 = 1, new2(X1, Y1, N).  
new2(X, Y, N) :- X = 1, Y = 1, N > 1, X1 = 2, Y1 = 3, new3(X1, Y1, N).  
new3(X, Y, N) :- X1 ≥ 1, Y1 ≥ X1, X < N, X1 = X + 1, Y1 = X1 + Y, new3(X1, Y1, N).  
new3(X, Y, N) :- Y ≥ 1, N > 0, X ≥ N, X > Y.
```

The fact `incorrect.` is not in VCs: we cannot infer that *increase* is **incorrect**.

A constrained fact is in VCs: we cannot infer that *increase* is **correct**.

Introduction of new definitions by generalization

1. incorrect :- $X=0, Y=0, \text{new1}(X,Y,N)$.
2. $\text{new2}(X,Y,N) :- X=1, Y=1, N>0, \text{new1}(X,Y,N)$.

Candidate new definition:

$\text{new3}(X_r, Y_r, N_r) :- X_r=1, Y_r=1, X=2, Y=3, N>1, \text{new1}(X,Y,N)$.

The transformation strategy might introduce infinitely many new definitions. Generalization is needed.

Generalization (based on widening):

3. $\text{new3}(X,Y,N) :- X \geq 1, Y \geq 1, N>0, \text{new1}(X,Y,N)$.

P:

```
incorrect :- a(X), p(X).  
p(X) :- c(X,Y), p(Y).  
p(X) :- b(X).
```



Reversal

RevP:

```
incorrect :- b(X), p(X).  
p(Y) :- c(X,Y), p(X).  
p(X) :- a(X).
```

$\text{incorrect} \in M(P)$ iff $\text{incorrect} \in M(\text{RevP})$

Specialized Verification Conditions for *increase*

`incorrect` :- $N > 0$, $X1 = 1$, $Y1 = 1$, `new2`($X1$, $Y1$, N).

`new2`(X , Y , N) :- $X = 1$, $Y = 1$, $N > 1$, $X1 = 2$, $Y1 = 3$, `new3`($X1$, $Y1$, N).

`new3`(X , Y , N) :- $X1 \geq 1$, $Y1 \geq X1$, $X < N$, $X1 = X + 1$, $Y1 = X1 + Y$, `new3`($X1$, $Y1$, N).

`new3`(X , Y , N) :- $Y \geq 1$, $N > 0$, $X \geq N$, $X > Y$.

Reversed VCs

`incorrect` :- $Y \geq 1$, $N > 0$, $X \geq N$, $X > Y$, `new3`(X , Y , N).

`new3`($X1$, $Y1$, N) :- $X1 \geq 1$, $Y1 \geq X1$, $X < N$, $X1 = X + 1$, $Y1 = X1 + Y$, `new3`(X , Y , N).

`new3`($X1$, $Y1$, N) :- $X = 1$, $Y = 1$, $N > 1$, $X1 = 2$, $Y1 = 3$, `new2`(X , Y , N).

`new2`($X1$, $Y1$, N) :- $N > 0$, $X1 = 1$, $Y1 = 1$.

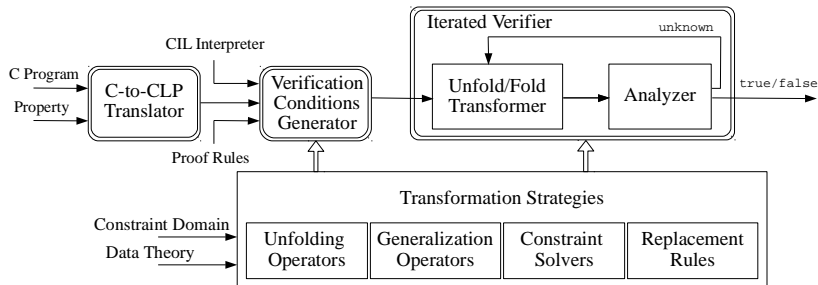
Specialized VCs

by propagating the constraint $Y \geq 1$, $N > 0$, $X \geq N$, $X > Y$.

`incorrect` :- $Y \geq 1$, $N > 0$, $X \geq N$, $X > Y$, `new4`(X , Y , N).

No constrained facts: *increase* is **correct**.

The VeriMAP tool <http://map.uniroma2.it/VeriMAP>
[DFPP PEPM 2013, VMCAI 2014, TACAS 2014]



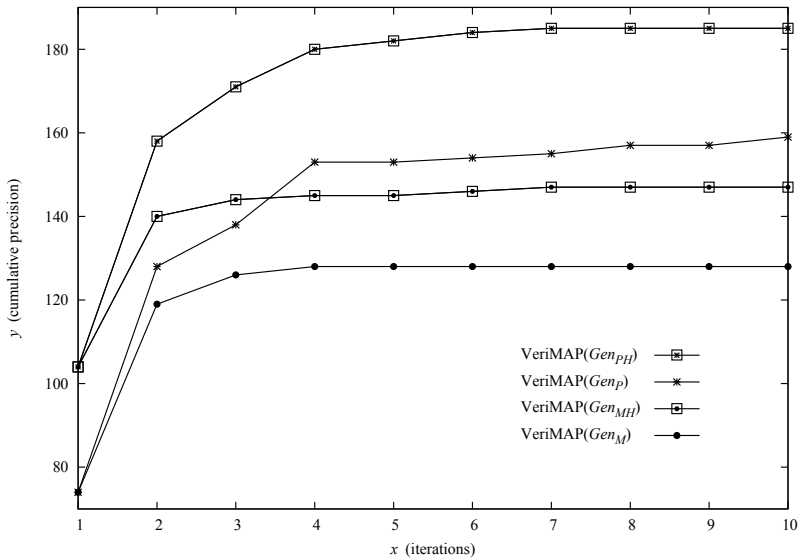
Experimental Evaluation

216 examples taken from: DAGGER, TRACER, InvGen, and TACAS 2013 Software Verification Competition.

		VeriMAP	ARMC	HSF(C)	TRACER
1	<i>correct answers</i>	185	138	160	103
2	<i>safe problems</i>	154	112	138	85
3	<i>unsafe problems</i>	31	26	22	18
4	<i>incorrect answers</i>	0	9	4	14
5	<i>false alarms</i>	0	8	3	14
6	<i>missed bugs</i>	0	1	1	0
7	<i>errors</i>	0	18	0	22
8	<i>timed-out problems</i>	31	51	52	77
9	<i>total score</i>	339 (0)	210 (-40)	278 (-20)	132 (-56)
10	<i>total time</i>	10717.34	15788.21	15770.33	23259.19
11	<i>average time</i>	57.93	114.41	98.56	225.82

- ARMC [Podelski, Rybalchenko PADL 2007]
- HSF(C) [Grebenshchikov et al. TACAS 2012]
- TRACER [Jaffar, Murali, Navas, Santosa CAV 2012]

Improving Precision by Iteration



Verifying Array Programs

An Example: Array Initialization.

Program *SeqInit*

```
i=1;
while(i < n) {
    a[i]=a[i-1]+1;
    i=i+1;
}
```


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An Execution

$[4, _, _, _] \implies [4, 5, _, _] \implies [4, 5, 6, _] \implies [4, 5, 6, 7]$

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$[4, _, _, _] \implies [4, 5, _, _] \implies [4, 5, 6, _] \implies [4, 5, 6, 7]$

Partial Correctness Specification

$\{i \geq 0 \wedge n = \text{dim}(a) \wedge n \geq 1\}$

SeqInit

$\{\forall j (0 \leq j \wedge j + 1 < n \rightarrow a[j] < a[j+1])\}$

The transition for *array assignment*

- *command*: $L : a[ie] = e$
- *store*: S
- *transition*:

```
tr(cf(cmd(L,asgn(elem(A,IE),E)),S),
   cf(cmd(L1,C),S1)) :-
    eval(IE,S,I),
    eval(E,S,V),
    lookup(S,array(A),FA),
    write(FA,I,V,FA1),
    update(S,array(A),FA1,S1),
    nextlab(L,L1),
    at(L1,C).
```

source configuration
target configuration
evaluate index expr
evaluate expression
get array from store
update array
update store
next label
next command

Partial Correctness Specification

$$\{i \geq 0 \wedge n = \text{dim}(a) \wedge n \geq 1\}$$
 φ_{init} *SeqInit*

$$\{\forall j (0 \leq j \wedge j + 1 < n \rightarrow a[j] < a[j+1])\}$$
 ψ

$$\{\exists j (0 \leq j \wedge j + 1 < n \wedge a[j] \geq a[j+1])\}$$
 $\varphi_{\text{error}} \equiv \neg\psi$

CLP encoding of incorrectness

```
incorrect :- initConf(X), reach(X).
```

```
reach(Y) :- tr(X,Y), reach(X).
```

```
reach(Y) :- errorConf(Y).
```

```
initConf(cf(firstCmd, [[int(i), I], [int(n), N], [array(a), A]])
        :- I ≥ 0, dim(A, N), N ≥ 1. |  $\varphi_{\text{init}}$ 
```

```
errorConf(cf(haltCmd, [[int(i), I], [int(n), N], [array(a), A]])
        :- 0 ≤ J, J + 1 < N, J1 = J + 1, AJ ≥ AJ1, |  $\varphi_{\text{error}}$ 
           read(A, J, AJ), read(A, J1, AJ1). |
```

CLP with array constraints

Array constraints

- $\text{read}(a, i, v)$ (the i -th element of array a is v)
- $\text{write}(a, i, v, b)$
(array b is equal to array a except that its i -th element is v)
- $\text{dim}(a, n)$ (the dimension of a is n)

Theory of Arrays \mathcal{A}

Array congruence

(AC) $I = J, \text{read}(A, I, U), \text{read}(A, J, V) \rightarrow U = V$

Read-over-Write

(RoW1) $I = J, \text{write}(A, I, U, B), \text{read}(B, J, V) \rightarrow U = V$

(RoW2) $I \neq J, \text{write}(A, I, U, B), \text{read}(B, J, V) \rightarrow \text{read}(A, J, V)$

The Constraint Replacement Rule

R5. Constraint Replacement :

If $\mathcal{A} \models \forall (c_0 \leftrightarrow (c_1 \vee \dots \vee c_n))$, where \mathcal{A} is the *Theory of Arrays*

Then replace $H :- c_0, d, G$

by $H :- c_1, d, G, \dots, H :- c_n, d, G$

Array congruence

(AC) $I = J, \text{read}(A, I, U), \text{read}(A, J, V) \rightarrow U = V$

[AC1] replace: $I = J, \text{read}(A, I, U), \text{read}(A, J, V)$
by: $I = J, \text{read}(A, I, U), U = V$

[AC2] replace: $U \neq V, \text{read}(A, I, U), \text{read}(A, J, V)$
by: $U \neq V, \text{read}(A, I, U), \text{read}(A, J, V), I \neq J$

Constraint Replacements using the Theory of Arrays (2)

Read-over-Write

(RoW1) $I = J$, `write(A, I, U, B)`, `read(B, J, V)` $\rightarrow U = V$

(RoW2) $I \neq J$, `write(A, I, U, B)`, `read(B, J, V)` \rightarrow `read(A, J, V)`

[RoW1] replace: $I = J$, `write(A, I, U, B)`, `read(B, J, V)`
by: $I = J$, `write(A, I, U, B)`, $U = V$

[RoW2] replace: $I \neq J$, `write(A, I, U, B)`, `read(B, J, V)`
by: $I \neq J$, `write(A, I, U, B)`, `read(A, J, V)`

[RoW12] replace: `write(A, I, U, B)`, `read(B, J, V)`
by: $I = J$, `write(A, I, U, B)`, $U = V$
and $I \neq J$, `write(A, I, U, B)`, `read(A, J, V)`

The Transformation Strategy with Constraint Replacement

Transform(P)

```
TransfP =  $\emptyset$ ;  
Defs = {incorrect :- initConf(X), reach(X)};  
while  $\exists cl \in$  Defs do  
  Cls = Unfold(cl);  
  Cls = ConstraintReplacement(Cls);  
  Cls = ClauseRemoval(Cls);  
  Defs = (Defs - {cl})  $\cup$  Define(Cls);  
  TransfP = TransfP  $\cup$  Fold(Cls, Defs);  
od
```

The Transformation Strategy with Constraint Replacement

Transform(P)

```
TransfP =  $\emptyset$ ;  
Defs = { incorrect :- initConf(X), reach(X) };  
while  $\exists cl \in$  Defs do  
  Cls = Unfold(cl);  
  Cls = ConstraintReplacement(Cls);  
  Cls = ClauseRemoval(Cls);  
  Defs = (Defs - {cl})  $\cup$  Define(Cls);  
  TransfP = TransfP  $\cup$  Fold(Cls, Defs);  
od
```

Theorem (Termination and Correctness of the Transformation Strategy)

- *Transform*(P) terminates for all P;
- **incorrect** \in M(P) iff **incorrect** \in M(TransfP)

Applying the Transformation Strategy

Generation of Verification Conditions;
Reversal;
Propagation of the Error Property.

Transformed VCs for *SeqInit*

```
incorrect :- J1=J+1, J ≥ 0, J1 < I, AJ ≥ AJ1, D=I-1, N=I+1, Y=X+1,  
  read(A, J, AJ), read(A, J1, AJ1), read(A, D, X), write(A, I, Y, B),  
  new1(I, N, A).  
new1(I1, N, B) :- I1=I+1, Z=W+1, Y=X+1, D=I-1, N ≤ I+2,  
  I ≥ 1, Z < I, Z ≥ 1, N > I, U ≥ V, read(A, W, U), read(A, Z, V),  
  read(A, D, X), write(A, I, Y, B), new2(I, N, A).  
new2(I1, N, B) :- I1=I+1, Z=W+1, Y=X+1, D=I-1, I ≥ 1,  
  Z < I, Z ≥ 1, N > I, U ≥ V, read(A, W, U), read(A, Z, V),  
  read(A, D, X), write(A, I, Y, B), new2(I, N, A).
```

No constrained facts: the program *SeqInit* is **correct**.

Experimental Evaluation: Array Programs

<i>Program</i>	<i>Gen_W</i>	<i>Gen_{WD}</i>	<i>Gen_S</i>	<i>Gen_{SD}</i>
<i>init</i>	<i>unknown</i>	0.06	0.10	0.08
<i>init-partial</i>	<i>unknown</i>	0.06	0.07	0.08
<i>init-non-constant</i>	<i>unknown</i>	0.06	0.22	0.22
<i>init-sequence</i>	<i>unknown</i>	0.80	<i>unknown</i>	1.20
<i>copy</i>	<i>unknown</i>	0.27	0.33	0.29
<i>copy-partial</i>	<i>unknown</i>	0.29	0.34	0.34
<i>copy-reverse</i>	<i>unknown</i>	0.27	0.46	0.45
<i>max</i>	<i>unknown</i>	0.31	0.24	0.33
<i>sum</i>	<i>unknown</i>	0.68	1.14	1.12
<i>difference</i>	<i>unknown</i>	0.66	1.15	1.11
<i>find</i>	0.25	0.43	0.46	0.45
<i>first-not-null</i>	0.38	0.41	0.42	0.42
<i>find-first-non-null</i>	1.24	1.87	1.94	1.93
<i>partition</i>	0.06	0.11	0.14	0.12
<i>insertionsort-inner</i>	0.21	0.26	0.45	0.43
<i>bubblesort-inner</i>	2.46	2.71	2.45	2.75
<i>selectionsort-inner</i>	7.20	6.40	7.23	7.16
<i>precision</i>	7	17	16	17
<i>total time</i>	11.80	15.65	17.14	18.48
<i>average time</i>	1.69	0.92	1.07	1.09

The GCD Program

```

x=m; y=n;
while(x != y) {
    if(x > y) x=x-y;
    else     y=y-x;
}
z=x;
// z is the GCD of m and n

```

Initial and error properties

$$\varphi_{init}(m,n) \equiv m \geq 1 \wedge n \geq 1$$

$$\varphi_{error}(m,n,z) \equiv \exists d (gcd(m,n,d) \wedge d \neq z)$$

GCD property

$$gcd(X,Y,D) :- X > Y, \quad X1 = X - Y, \quad gcd(X1, Y, D).$$

$$gcd(X,Y,D) :- X < Y, \quad Y1 = Y - X, \quad gcd(X, Y1, D).$$

$$gcd(X,Y,D) :- X = Y, \quad Y = D.$$

CLP encoding of GCD

```

incorrect :- initConf(X), reach(X).
reach(Y) :- tr(X,Y), reach(X).
reach(Y) :- errorConf(Y).
initConf(cf(cmd(0, asgn(int(x), int(m))),
  [[int(m), M], [int(n), N], [int(x), X], [int(y), Y], [int(z), Z]])) :-
  M ≥ 1, N ≥ 1. φinit(m,n)
errorConf(cf(cmd(h, halt),
  [[int(m), M], [int(n), N], [int(x), X], [int(y), Y], [int(z), Z]])) :-
  gcd(M, N, D), D ≠ Z. φerror(m,n,z)

```

Generation of VCs; Reversal; Propagation of $\varphi_{error}(m,n,z)$

Transformed GCD

```

incorrect :- M ≥ 1, N ≥ 1, M > N, X1 = M - N, Z ≠ D, new2(M, N, X1, N, Z, D).
incorrect :- M ≥ 1, N ≥ 1, M < N, Y1 = N - M, Z ≠ D, new2(M, N, M, Y1, Z, D).
new2(M, N, X, Y, Z, D) :- M ≥ 1, N ≥ 1, X > Y, X1 = X - Y, Z ≠ D, new2(M, N, X1, Y, Z).
new2(M, N, X, Y, Z, D) :- M ≥ 1, N ≥ 1, X < Y, Y1 = Y - X, Z ≠ D, new2(M, N, X, Y1, Z).

```

No constrained fact: The *gcd* program is correct.

Why Use CLP Transformation for Verification?

- CLP transformation can be used both for *generating* VCs and for *proving* their satisfiability

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 - programming language and its operational semantics
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Why Use CLP Transformation for Verification?

- CLP transformation can be used both for *generating* VCs and for *proving* their satisfiability
- CLP transformation is *parametric* with respect to:
 - programming language and its operational semantics
 - properties and proof rules
 - theory of data structures
- The input and the output of transformation are semantically equivalent CLP programs.
 - *incremental verification*
 - *composition* of transformations for refining verification

Future Work

- Recursive functions
- More data structure theories (lists, heaps, etc.)
- Other programming languages, properties, proof rules

Thanks for your attention!

Try the VeriMAP tool <http://map.uniroma2.it/VeriMAP>